# Effect of Peripheral Afferent Alteration of the Lateral Ankle Ligaments on Dynamic Stability\*

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**Background:** The sensorimotor influence of the lateral ankle ligaments in muscle activation is unclear. **Hypothesis:** The lateral ankle ligaments have significant sensorimotor influence on muscle activation.

Study Design: Controlled laboratory study.

**Methods:** Muscle-firing characteristics in response to a high-speed inversion perturbation and during gait were assessed in 13 normal subjects. Solutions (1.5% lidocaine or a placebo of saline) were injected bilaterally into the anterior talofibular and calcaneofibular ligaments (1.5 ml per ligament) to alter peripheral afferent influence. Subjects were again tested with the same protocol.

**Results:** The protective response of the anterior tibialis and peroneal muscles during inversion perturbation and mean muscle activation amplitude decreased during running after both injections. After injection, no significant differences were seen for muscle reflex latencies, maximum amplitude, time to maximum amplitude during inversion perturbation, or mean amplitude during walking.

Conclusion: The lateral ankle ligaments have a sensorimotor influence on muscle activation.

Clinical Relevance: Induced edema from the injected solutions may have altered the sensorimotor influence of the lateral ankle ligaments, thereby inhibiting the dynamic ankle stabilizers. This finding suggests that dynamic stability may be compromised because of swelling after joint injury.

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Much has been written about the mechanical role of the ligaments that surround the ankle joint in providing ankle joint stability. <sup>22,30,34,35,56</sup> The anterior talofibular ligament limits talar tilt throughout sagittal plane motion, especially with the joint in a position of plantar flexion. <sup>30,56</sup> The calcaneofibular ligament appears to limit talar tilting in dorsiflexion as well as in talocalcaneal adduction. <sup>22,34,35</sup>

anoreceptors believed to be responsible for providing a proprioceptive role in maintaining ankle joint stability. <sup>15</sup> Proprioception, which results from the afferent neural input originating from mechanoreceptors about the joint, contributes to dynamic joint stability mechanisms and coordinated motor patterns. <sup>42</sup> Michelson and Hutchins <sup>50</sup> demonstrated histologically that Ruffini-type, Pacinian corpuscle type, and Golgi tendon organ receptors are dispersed throughout the ankle ligaments, with Pacinian and Golgi tendon-like organs making up a majority of the mechanoreceptors present. Johansson and colleagues <sup>27</sup> described how ligamentous mechanoreceptors like these play a role in providing joint stability that is equally as important as the purely mechanical role of the ligaments.

By use of traction forces well below those associated with

In addition, embedded within these ligaments are mech-

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tissue damage and nociception, stimulation of the ligamentous mechanoreceptors has been demonstrated to have potent effects on sensitivity and activation of the gamma motor neurons associated with the muscle spindle. <sup>27,28,51,57,63</sup> These potent effects provide significant contributions to muscle stiffness, motor control, and reflexive characteristics. <sup>28,29</sup> Except for temporal assessment of reflex latencies, <sup>8,13,24,31,33,37–39,44,47</sup> no research has specifically measured the contribution of ankle ligament mechanoreceptors to muscle-firing characteristics associated with joint stability. It is feasible that the influence of these mechanoreceptors on muscle-firing characteristics may have nontemporal implications, such as amplitude of muscle activation, which may be overlooked in temporal (latency) assessments.

The peripheral afferent contribution of ligamentous mechanoreceptors on neuromuscular mechanisms, such as muscle-firing characteristics, has been measured by using anesthesia to block them. Feuerbach et al. 14 injected lateral ankle ligaments with an anesthetic to block peripheral afferent influence, thereby determining the role that ligaments play in supplying joint proprioception. Both Hertel et al.20 and DeCarlo and Talbot9 injected an anesthetic into the lateral ankle ligaments to ascertain the role of peripheral afferent information from these ligaments in postural control tasks. Thus far, two groups have examined muscle reflex latencies of dynamic restraints after injection into lateral ankle ligaments; both failed to reveal significant latency changes in healthy subjects. 33,39 However, because of the influence of ligamentous mechanoreceptors on gamma reflex loops, 27, 28, 51, 57, 63 it is plausible that they mediate other characteristics of the response; to date, no research has considered this possibility. Furthermore, we are unaware of any research that has examined the influence of the lateral ankle ligaments on musclefiring characteristics during dynamic tasks such as walking and running. The purpose of this study was to evaluate the role of peripheral afferent information from the lateral ankle ligaments in spatial and temporal muscle activation characteristics during an inversion perturbation and during dynamic gait tasks such as walking and running.

## **METHODS**

Thirteen subjects (seven men,  $24.7 \pm 4.2$  years of age with a height of  $180.1 \pm 6.1$  cm and mass of  $78.8 \pm 6.8$  kg; and six women,  $22.3 \pm 0.95$  years of age with a height of  $162.6 \pm 6.8$  cm and mass of  $62.3 \pm 5.2$  kg) participated in this study. All subjects were right-leg dominant (operationally defined as the foot the subject would use to kick a ball) and had no significant history of lower extremity injury. Informed consent was obtained before participation, in accordance with the requirements of the University of Pittsburgh Institutional Review Board. Each subject attended two testing sessions at least 48 hours apart. A pretest-posttest research design was used during each session.

### Instrumentation

The ankle inversion perturbation device is a specially designed platform that allows the ankle joint to drop from a neutral position into 30° of inversion while the subject is standing (Fig. 1). Both right and left plates of the platform are connected to two tension springs that pull each plate down into 30° of inversion at an average angular velocity of 440 deg/sec. The plates are held level by spring plungers connected to two independent levels that release each plate independently when triggered, inducing the inversion perturbation. Each plate is fitted with a 2g accelerometer (Newh Ghant Technologies, LaGrangeville, New York) to signal onset of platform drop. The inversion plates are positioned over a Bertec forceplate (Model #K80801, Type 4060-10, Bertec Corporation, Columbus, Ohio) to ensure equal weight distribution between limbs at the time of perturbation. Pilot testing of the device to establish reliability for measurement of muscle-firing characteristics was performed on 15 subjects and yielded intraclass correlation coefficients (2,1) ranging from 0.71 to 0.76, with standard error of measurement of 6.1 to 8.2 msec calculated according to Denegar and Bell<sup>11</sup> and Shrout and Fleiss.60

# Electromyographic Instrumentation and Preparation

Electromyographic data were collected with the Noraxon Telemyo (Noraxon, Scottsdale, Arizona) EMG system, a



**Figure 1.** A subject positioned on the ankle inversion perturbation device.

frequency modulated (FM) telemetry system. Electromyographic signals collected from the electrodes were passed through a single-ended amplifier (gain 500) to an eightchannel FM transmitter. A receiver unit obtained the telemetry signals from the transmitter, where the receiver amplified (gain 500) and filtered (15 Hz low-pass, 500 Hz high-pass Butterworth filter, common mode rejection ratio of 130 db) the signals. Signals from the EMG receiver, force plate, and acceleration were converted from analog to digital data via a PCM16S/12 (16-channel, 12-bit) analog-to-digital board (ComputerBoards, Inc., Middleboro, Massachusetts) at a rate of 1000 Hz. The digital data were collected and stored with Myoresearch 2.02 (Noraxon) on a personal computer for later data reduction.

Silver-silver chloride surface electrodes (Medicotest, Inc., Rolling Meadows, Illinois) were used for measurement of muscle activity. Skin preparation to lower impedance included shaving any hair present, mild abrasion with a low-abrasive emery board, and wiping the area with 70% isopropyl alcohol. A ground electrode was placed just distal to the tibial tuberosity, and two surface electrodes were placed side by side and perpendicular to the orientation of the anterior tibialis, peroneus longus, and peroneus brevis muscle fibers, with 2 cm separating their centers. 6,10 The same investigator applied electrodes on all subjects during all sessions to control for intertester variability. The peroneal muscles were chosen because of their everter function, reported activity during the stance phase of gait when the ankle is at risk of injury, and for the role they play in dynamic balance during gait tasks. 46 The anterior tibialis muscle was chosen because of its function as an antagonist to the peroneal muscles. 46 Correct position of all electrodes was confirmed through isolated manual muscle tests of each muscle.6 Komi and Buskirk<sup>36</sup> established the reliability of surface electrode EMG as 0.88 to 0.91 intraclass correlation coefficient within sessions and 0.64 to 0.73 intraclass correlation coefficient between testing sessions.

Stance and swing phases of the walking and running tasks were identified with the NorSwitch (Noraxon) foot switch system, which uses pressure-sensitive resistors that output consistent voltage to signal gait events. The pressure-sensitive foot switches were secured to the calcaneus and to the first ray on the plantar surface of the foot.

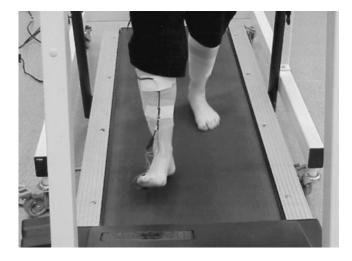
### **Testing Procedures**

Once informed consent and EMG preparation was completed, each subject was oriented to the testing procedures. For inversion perturbation testing, all subjects were asked to stand barefoot on the platform with the second ray of both feet aligned with the axis of rotation of the plates and with their hands placed on their hips. Subjects were asked to wear a blindfold and a headphone set emitting white noise to negate visual and auditory cues. Before the start of the inversion trials, the subjects were asked to maintain a quiet stance on the platform for a period of 12 seconds. During that time, center of pressure and EMG activity were assessed. Immediately after

the quiet stance, 12 randomized pretest inversion trials (6 trials per limb) were performed. Subjects were unaware of which platform would drop for each trial. These pretest trials served as control trials for comparison of muscle activity before and after injection of the solution.

During the dynamic gait activities, subjects were asked to walk and run barefoot on a treadmill (Biodex Treadmill, Biodex Medical, Shirley, New York) (Fig. 2). Treadmill speeds were standardized at 3.2 km/hr and 7.6 km/hr for walking and running, respectively. Subjects were instructed to walk and run using their normal gait mechanics. The subjects were not allowed to touch the handrails of the treadmill to eliminate the influence that external support has on muscle-firing patterns during gait. 46 Subjects were given ample time for familiarization with the treadmill and speed of movement before trial recording. Once the standardized speed was obtained and the subject indicated that a fluid gait pattern was achieved, EMG and foot switch recording was initiated. Recording of the EMG and foot switch signals continued until at least 20 strides were completed, allowing for analysis of 12 strides for all trials. A review of the literature indicated that at least six strides are needed to obtain a representative EMG profile during gait activity.4,59,73

Immediately after pretesting, a physician injected either 1% preservative-free lidocaine HCl (Astra USA, Inc., Westborough, Massachusetts) or a placebo solution (preservative-free 0.9% sodium chloride, Abbott Laboratories, North Chicago, Illinois) with a 25-gauge 5/8-inch syringe into both the anterior talofibular and calcaneofibular ligament regions (1.5 ml for each site) of each ankle (Fig. 3). 14,20 Subjects, who were blinded as to which solution was being injected, were asked to remain inactive for 20 minutes after injection to allow for induction of the anesthetic effects. Subjects were again tested with identical inversion perturbation and treadmill protocols. Testing protocols were alternated within testing sessions. Subjects returned for a second session at least 48 hours after the initial session and were tested with identical procedures but were injected with the other solution.



**Figure 2.** Assessment of muscle activity during dynamic activities on the treadmill.





**Figure 3.** Injection into the anterior talofibular (A) and calcaneofibular (B) ligaments.

# Data Reduction

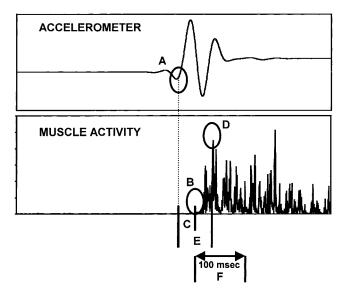
Inversion Perturbation. Because limb dominance has been demonstrated to cause differences between limbs, only the dominant limb was analyzed. 13,24 This decision was justified because the purpose of the investigation was not to measure bilateral differences but to measure changes after peripheral afferent alteration, which can be accomplished by making comparisons within the same limb. Subjects were unaware that only the data from the dominant limb would be considered. Accelerometer, EMG, and force plate data were exported and conditioned with LabVIEW 5.1 customized software (National Instruments, Austin, Texas). Force and moment data obtained by the force plate and accelerometer were filtered with a 10-Hz cutoff, fourth-order zero-phase lag Butterworth filter. 70 Trial EMG data were rectified, filtered (20 to 500 Hz bandpass fourth-order zero-phase lag Butterworth filter), and normalized to the mean amplitude of a rectified filtered linear envelope for each respective muscle during the quiet stance trial.<sup>67</sup>

Perturbation onset and muscle-firing characteristics were calculated with customized software written in Visual Basic for Applications (Microsoft, Redmond, Washington). Perturbation onset was determined by using the acceleration data. Muscle activation onset was ascertained by using a similar algorithm of five standard deviations above baseline activity 150 msec before perturbation. This method of determining onset has been proven reliable. The customized software allowed user interaction so that a reviewer could subjectively accept or reject data that contained nonphysiologic activity, similar to the method described by Di Fabio 2 and Lynch et al.

The customized software calculated the *maximum amplitude*, defined as the maximum amplitude of EMG activity within 100 msec after muscle onset. *Time to maximum amplitude* was defined as the time from perturbation onset to maximum amplitude. The *protective response*, the mean amplitude of the window from muscle activity onset to 100 msec after onset, was calculated. <sup>44</sup> Figure 4 illustrates the measured muscle-firing characteristics.

Center-of-pressure standard deviation in the mediolateral direction was calculated from the force and moment data and compared with the center of pressure for both the quiet stance and the window from 150  $\mu$ sec before perturbation to perturbation onset to avoid unequal limb loading due to subject anticipation. Any deviation in the center of pressure three times that during quiet stance indicated that unequal weight distribution occurred, invalidating that trial. Invalid trials were discarded.

Muscle Activity during Gait. Raw EMG signals for all muscles were both rectified and second-order low-pass Butterworth filtered (6 Hz cutoff). Stance and swing phases of the walking and running tasks were visually identified by the foot switch signals within the Myoresearch software. Twelve complete gait cycles were estab-



**Figure 4.** Muscle reflex characteristics. A, ankle perturbation onset; B, muscle reflex onset; C, muscle reflex latency; D, maximum amplitude; E, time to maximum amplitude; and F, muscle protective response.

lished for analysis and were normalized to both time and mean amplitude for the gait cycle for establishment of a linear envelope. The mean amplitude for both stance and swing phases was used for statistical analysis.

### Statistical Analysis

Statistical analysis for each dependent variable consisted of separate (two within and one between) repeated-measures analysis of variance models. The within factors were test (pretest versus posttest) and muscle (anterior tibialis, peroneus longus, and peroneus brevis), and the between factor was treatment (placebo versus anesthetic). Although each subject received both anesthesia and placebo treatments, the weak reliability of between-session comparisons for surface EMG results demonstrated in the literature warranted analyzing the two treatments as a between factor rather than a within factor in the analysis of variance model.  $^{36}$  A Tukey post hoc analysis was used for pairwise comparisons of significant results (P < 0.05)

# **RESULTS**

### Inversion Perturbation Reflex Characteristics

The descriptive statistics for muscle latency, maximum amplitude, time to maximum amplitude, and protective muscle response appear in Tables 1 to 4, respectively. Statistical analysis revealed no significant difference within or between factors for muscle latency, maximum amplitude, and time to maximum amplitude. A test main effect (F[1,24] = 11.10, P = 0.03) did manifest for the protective muscle response. These results indicated suppressed muscle activity after injection of either solution into the lateral ankle ligaments (Fig. 5).

### Dynamic Activity Muscle-Firing Characteristics

The descriptive statistics for mean amplitudes of each muscle during both the stance and swing phase while walking and running appear in Tables 5 and 6. For analysis of the gait data, separate repeated-measures analysis of variance models demonstrated decreased mean amplitude of the per-

TABLE 1 Muscle Reflex Latency in Milliseconds (Mean  $\pm$  SD)

| Muscle  | Anesthesia  |   | Placebo   |  |
|---|---|---|---|--|
| Muscie  | Pretest   | Posttest  | Pretest   | Posttest   |
| Anterior tibialis<br>Peroneus longus<br>Peroneus brevis | $87.92 \pm 15.21$<br>$88.92 \pm 9.95$<br>$81.38 \pm 8.79$ | $\begin{array}{c} 94.26 \pm 15.71 \\ 89.94 \pm 7.38 \\ 83.39 \pm 10.06 \end{array}$ | $98.20 \pm 19.66 \\ 89.61 \pm 15.40 \\ 84.78 \pm 14.20$ | $\begin{array}{c} 91.59 \pm 15.05 \\ 90.04 \pm 15.43 \\ 85.36 \pm 12.09 \end{array}$ |

TABLE 2 Maximum Muscle Ampitude<sup>a</sup> (Mean  $\pm$  SD)

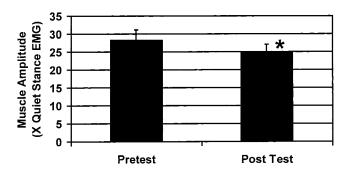
| Muscle                             | Anesthesia                          |                                     | Placebo                             |  |
|------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|--|
|                                    | Pretest                             | Posttest                            | Pretest                             | Posttest                               |
| Anterior tibialis                  | $49.29 \pm 43.59$                   | $34.54 \pm 31.55$                   | $48.04 \pm 46.17$                   | $45.54 \pm 34.26$                      |
| Peroneus longus<br>Peroneus brevis | $36.00 \pm 23.47 \ 43.19 \pm 21.70$ | $41.53 \pm 19.22 \ 43.77 \pm 17.37$ | $49.66 \pm 37.04 \ 41.62 \pm 15.29$ | $47.18 \pm 34.28$<br>$41.73 \pm 18.09$ |

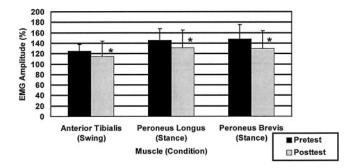
<sup>&</sup>lt;sup>a</sup> Muscle amplitudes are normalized to quiet stance and listed as a percentage of quiet stance EMG amplitude.

| Muscle            | Anesthesia        |                   | Placebo           |                   |
|-------------------|-------------------|-------------------|-------------------|-------------------|
|                   | Pretest           | Posttest          | Pretest           | Posttest          |
| Anterior tibialis | $118.94 \pm 22.7$ | $117.05 \pm 23.3$ | $126.39 \pm 24.2$ | $118.71 \pm 19.7$ |
| Peroneus longus   | $105.21 \pm 14.5$ | $107.02 \pm 14.0$ | $109.34 \pm 20.1$ | $107.41 \pm 15.3$ |
| Peroneus brevis   | $111.37\pm14.9$   | $113.97 \pm 19.5$ | $115.10\pm22.7$   | $113.08 \pm 16.2$ |

| Muscle  | Anesthesia  |   | Placebo   |   |
|---|---|---|---|---|
| Muscie  | Pretest   | Posttest  | Pretest   | Posttest  |
| Anterior tibialis<br>Peroneus longus<br>Peroneus brevis | $31.99 \pm 18.31$<br>$29.56 \pm 17.60$<br>$28.80 \pm 17.13$ | $25.64 \pm 20.36$<br>$25.24 \pm 13.85$<br>$26.14 \pm 17.62$ | $31.16 \pm 22.53$<br>$24.87 \pm 13.15$<br>$24.14 \pm 13.39$ | $28.83 \pm 21.72 \ 21.49 \pm 11.67 \ 23.18 \pm 13.96$ |

<sup>&</sup>lt;sup>a</sup> Muscle amplitudes are normalized to quiet stance and listed as a percentage of quiet stance EMG amplitude.





**Figure 5.** Muscle reflex protective response. \*, significantly different from pretest mean amplitude.

**Figure 6.** Mean EMG amplitude during running. \*, significantly different from pretest amplitudes.

| Muscle            | Anesthesia         |                    | Placebo            |                    |
|-------------------|--------------------|--------------------|--------------------|--------------------|
|                   | Pretest            | Posttest           | Pretest            | Posttest           |
| Stance phase      |                    |                    |                    |                    |
| Anterior tibialis | $79.66 \pm 10.42$  | $76.67 \pm 21.19$  | $70.81 \pm 11.15$  | $72.70 \pm 18.90$  |
| Peroneus longus   | $115.77 \pm 10.42$ | $103.65 \pm 23.00$ | $115.29 \pm 15.20$ | $115.02 \pm 42.04$ |
| Peroneus brevis   | $109.57 \pm 10.95$ | $100.11 \pm 17.99$ | $114.52 \pm 12.60$ | $107.40 \pm 35.16$ |
| Swing phase       |                    |                    |                    |                    |
| Anterior tibialis | $148.15 \pm 20.94$ | $135.46 \pm 31.43$ | $154.69 \pm 18.51$ | $154.94 \pm 34.01$ |
| Peroneus longus   | $59.78 \pm 26.31$  | $53.95 \pm 33.23$  | $72.54 \pm 26.40$  | $62.80 \pm 31.39$  |
| Peroneus brevis   | $61.01 \pm 18.00$  | $82.02 \pm 49.48$  | $72.58 \pm 22.85$  | $68.93 \pm 24.86$  |

<sup>&</sup>lt;sup>a</sup> Values expressed as percentage of the mean activity over the entire gait cycle.

| Muscle            | Anesthesia         |                    | Placebo            |                    |
|-------------------|--------------------|--------------------|--------------------|--------------------|
|                   | Pretest            | Posttest           | Pretest            | Posttest           |
| Stance phase      |                    |                    |                    |                    |
| Anterior tibialis | $78.79 \pm 10.64$  | $67.97 \pm 19.48$  | $67.41 \pm 15.66$  | $71.85 \pm 23.44$  |
| Peroneus longus   | $150.81 \pm 20.47$ | $129.01 \pm 27.83$ | $139.65 \pm 24.30$ | $132.93 \pm 40.73$ |
| Peroneus brevis   | $142.33 \pm 22.92$ | $127.45 \pm 42.80$ | $153.89 \pm 31.65$ | $131.34 \pm 24.59$ |
| Swing phase       |                    |                    |                    |                    |
| Anterior tibialis | $120.30 \pm 10.61$ | $108.29 \pm 32.71$ | $128.84 \pm 13.54$ | $121.06 \pm 24.10$ |
| Peroneus longus   | $51.92 \pm 16.41$  | $48.70 \pm 23.57$  | $63.69 \pm 22.06$  | $53.20 \pm 18.72$  |
| Peroneus brevis   | $61.01 \pm 18.00$  | $57.84 \pm 28.86$  | $55.96 \pm 17.28$  | $53.44 \pm 16.80$  |

<sup>&</sup>lt;sup>a</sup> Values expressed as percentage of the mean activity over the entire gait cycle.

oneus longus muscle during the swing phase of walking  $(F[1,24]=6.10,\ P=0.021)$ , the anterior tibialis muscle during the swing phase of running  $(F[1,24]=5.33,\ P=0.03)$ , and the peroneus longus  $(F[1,24]=8.07,\ P=0.009)$  and peroneus brevis muscles  $(F[1,24]=10.62,\ P=0.003)$  during the stance phase of running between pretest and posttest  $(Fig.\ 6)$ . No significant differences existed between the lidocaine and placebo solution conditions.

# DISCUSSION

The mechanical role of the anterior talofibular and calcaneofibular ligaments on ankle joint stability has been established. <sup>22,30,34,35,56</sup> It is believed that lateral ankle ligament injury results in not only mechanical instability <sup>40,58</sup> but also ligamentous deafferentation, contributing to instability. <sup>15,38,66</sup> Unfortunately, the sensorimotor influence of the lateral ankle ligaments is not completely

understood. The purpose of this study was to gain a better understanding of their sensorimotor role through alteration of the peripheral afferent influence that these ligaments may have on muscle-firing characteristics by using a previously described lidocaine model. 9,14,20,33,39 Activities that resemble the mechanism of lateral ankle ligament injuries (inversion perturbation) and the type of activities that are performed when these injuries are sustained (dynamic activities like running) were chosen to assess these sensorimotor influences.

### Inversion Perturbation Muscle Reflex Characteristics

It was predicted that peripheral afferent alteration of the lateral ankle ligaments with lidocaine would influence the muscle reflex characteristics of the dynamic stabilizers of the ankle joint. Results from this study indicated that this was not the case. Similar to previous reports, <sup>33,39</sup> periph-

eral afferent alteration with a lidocaine model had no significant effect on muscle reflex latencies. Unlike these previous investigations, however, this study also included measurement of reflex amplitude characteristics (maximum amplitude and protective mechanism) after peripheral afferent alteration. Again, however, lidocaine injection had no significantly different effect compared with that of the placebo solution.

A test main effect was present for the protective mechanism measured. This result demonstrated that injection of a solution (independent of which solution was injected) caused decreased muscle-firing amplitude over a 100msec period after muscle onset (Fig. 5). Because the results were independent of which solution was injected, a mechanism other than anesthesia was most likely responsible. Injection of solution into the ligament region possibly induced artificial swelling similar to that seen with injury. Unfortunately, we are unaware of any published data assessing the effects of edema and joint effusion on muscle-firing characteristics at the ankle joint. The effects of joint effusion, whether through joint injury or injection of saline solution, on muscle-firing characteristics have been reported at the knee, however. Knee joint effusion has been shown to have potent inhibitory effects on motoneuron pool recruitment, strength, and muscle activity of the quadriceps muscle. 23,25,32,64,65 As with reported results in the knee, injection of fluid into the ankle joint may inhibit the musculature that surrounds the ankle.

The question exists as to why both the lidocaine and the placebo saline solution would have an inhibitory effect on muscle-firing characteristics. Spencer et al.<sup>64</sup> demonstrated that injection of saline solution into the knee joint had inhibitory effects on the quadriceps muscle, but the addition of lidocaine to the knee joint curbed the quadriceps muscle inhibitory effects. In contrast, Agostinucci<sup>1</sup> reported no difference in soleus muscle motoneuron excitability between anesthetic and placebo conditions. Any suspected differences between the lidocaine and placebo conditions, like those in the knee, may be less pronounced in the ankle because type I Ruffini receptors are most likely responsible for the inhibitory response associated with joint pressure,64 and there is a lack of Ruffini receptors compared with type II and type III receptors in the ankle ligaments and joint capsule. 50,72 Another causative factor for suppressed muscle activity for both conditions might have been the insertion of the needle, but data presented by Jensen and Graf<sup>26</sup> demonstrated that the insertion of a catheter had no effect on quadriceps muscle inhibition, as measured by isokinetic strength. More research is needed to examine the influence of edema on reflex muscle-firing characteristics about the ankle joint as well as the role that anesthesia plays in affecting these characteristics.

# Dynamic Gait Muscle-Firing Characteristics

Similar results were seen from the analysis of muscle activity during the walking and running tasks. No differences between solutions existed within muscles before and after injection of solution during the stance or swing phases of both walking and running activities. Test main effects were also present, indicating decreased muscle amplitude after injection of solution (independent of which solution was injected). During running trials, the mean amplitude of peroneal muscles decreased during the stance phase of running and the anterior tibialis muscle mean amplitude was depressed during the swing phase (Fig. 6). Peroneus longus muscle activity also decreased during the swing phase of walking.

Comparison of the dynamic activity data was difficult, given the lack of published data examining the influential role that lateral ankle ligaments play on muscle-firing characteristics during dynamic gait activities. Again, some references can be made to the research about the knee. The results indicate decreased muscle activity during gait after injection of solution. The existence of some induced edema may have influenced the muscle activity. Torry et al.65 demonstrated quadriceps muscle activity from artificially induced knee joint effusion during gait activities that contributed to a quadriceps muscle avoidance gait pattern. Similar to the suppressed muscle activity at the knee resulting from induced joint effusion, ankle muscle-firing characteristics may have been altered with the induction of solution into the lateral ankle ligament, inducing edema accumulation similar to that with injury.

## Clinical Significance

Interpretation of these results suggests that the injection of solution (independent of which solution was injected) resulted in suppressed muscle activity both during inversion perturbation and dynamic activities. The accumulation of fluid within the lateral ankle, similar to the edema formation that exists with ankle injury, would suggest that not only is mechanical stability compromised because of the ligamentous trauma, but dynamic stability mechanisms may also be affected. The suppressed activity may compromise dynamic stability during the weightbearing position during dynamic activities when the ankle is vulnerable to injury. <sup>16</sup>

The consequence of this suppressed activity by the peroneal muscles is the decreased intrinsic stiffness that exists at the ankle joint. Intrinsic stiffness is obtained from mechanical properties of both muscle and passive components about the joint. <sup>17,53</sup> Intrinsic stiffness is strongly influenced by the level of muscle contraction present. <sup>69</sup> As muscle contraction increases, stiffness also increases. <sup>7,45,48,52,54,68,74</sup> Muscle contraction creates stable crossbridges that resist stretch while assisting with the storage of muscle energy. <sup>5</sup> Intrinsic stiffness provides the first line of defense for joint stability when force is applied to the joint. <sup>2,3,7,49,61,62</sup> Intrinsic stiffness provides an immediate and substantial response to perturbation. <sup>43</sup> Therefore, when some type of injury inversion mechanism occurs, the dynamic restraints system will be less likely to prevent the perturbing force from injuring the ankle joint when muscle activity is suppressed.

The suppressed activity of the ankle dynamic stabilizers during inversion perturbation is also problematic. When a destabilizing event like an inversion mechanism does occur, the magnitude of the muscular response, as measured by the 100-msec protective response, <sup>44</sup> to protect the ankle may also compromise joint stability. Some authors suggest that joint injury, such as that associated with an inversion mechanism, happens too fast for the reflex activity and accompanying force production to stiffen the joint to prevent the injurious mechanisms. <sup>19,41,49,55,61,62</sup> This hypothesis suggests that reflexive activity plays less of a role than does the intrinsic stiffness associated with joint stability. More research is needed on the role that reflexive activity plays in providing joint stability.

Because the injection of either solution elicited a change in muscle activity, rather than lidocaine as compared with placebo, as hypothesized, more research is needed to determine whether the resulting edema had an effect on muscle-firing characteristics during both the dynamic gait and inversion perturbation activities. In addition, in vivo models are needed in which the proprioceptive role of ankle ligaments in joint stability can be examined, given that joint deafferentation is often described as a contributor to functional instability and "giving way" episodes. 15,21,38,66 It may be that the proprioceptive influence of the ankle ligaments contributes more to joint position awareness and postural control capabilities rather than to muscle-firing patterns.

# **CONCLUSIONS**

The results of this study failed to demonstrate differences in muscle-firing characteristic between lidocaine and placebo treatment for both dynamic gait activities and during inversion perturbation. The results do indicate that the lateral ankle ligaments play a sensorimotor role as evidenced by the muscle suppression that manifested after the solution injection. Suppressed muscle activity was demonstrated by decreased muscle-firing amplitude during the stance and swing phases of gait activities and the reflexive response of the ankle dynamic stabilizers. Clinically, this result suggests that dynamic stability may be compromised due to swelling after joint injury or injection of fluid.

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